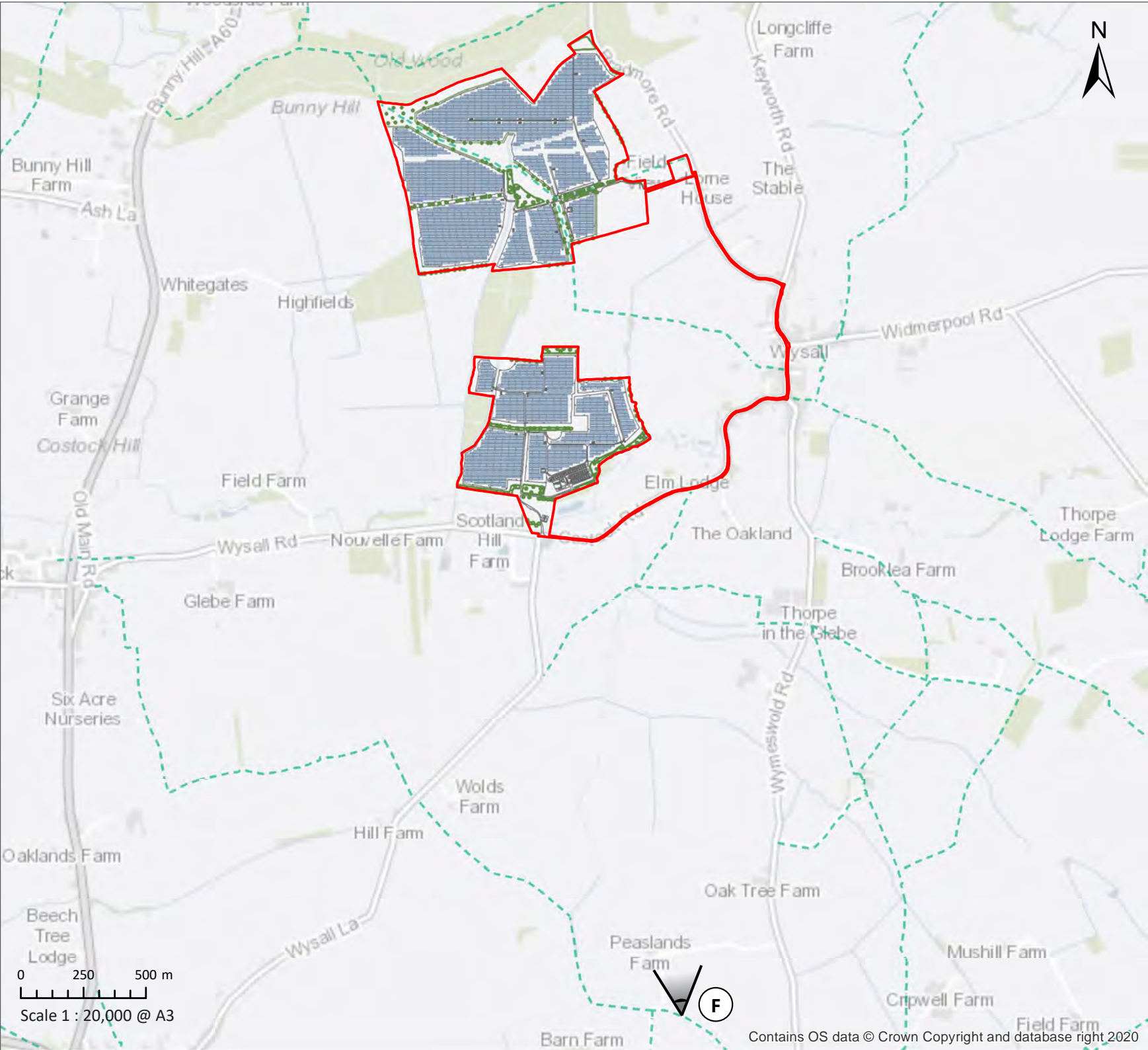


7.0 Viewpoint F Data Sheet

Viewpoint location plan



Viewpoint description

View from PRoW LT || H62/1 footpath looking north

Viewpoint F tripod location



View information

Visualisation Type:	4
Projection:	Cylindrical
Enlargement Factor:	150%
Date & time of photo:	01/08/2024 @ 10:21
Camera/sensor:	Canon EOS 6D Mk II
Camera lens:	50mm fixed
Camera height:	1.6m
Max aperture:	F13
HFoV:	53.5°
Distance to site:	2.1km
Direction:	354° from north
Frame Type:	Panorama
Viewpoint location:	E: 460047 N: 324627
Viewpoint ground height:	90 m AOD
Sheet size:	A1
Weather:	Sunny intervals
Visibility:	Good
Page viewing distance:	400mm (comfortable arms length)



Viewpoint F Existing View

All scale representative views to be viewed at a comfortable arms length

Please note: To view this image digitally, calibrate this scale bar on screen, for a correct scale representation, view the printed A1 sheet at a comfortable arm's length



Viewpoint F Proposed View Year 1

All scale representative views to be viewed at a comfortable arms length

Please note: To view this image digitally, calibrate this scale bar on screen, for a correct scale representation, view the printed A1 sheet at a comfortable arm's length



Viewpoint F Proposed View Year 15

All scale representative views to be viewed at a comfortable arms length

8.0 Methodology

- 8.1. The purpose of the visual representations is to accurately and objectively demonstrate the proposed development in-situ, using standardised and best practice guidelines. This is to aid and facilitate in the planning and decision-making process.
- 8.2. The following information is true, and has been prepared and provided in accordance with the current professional guidelines*
- 8.3. The viewpoint photographs panoramas and camera GPS locations were created by FTR Visuals in consultation with Exagen.
- 8.4. The following visualisations are based on Exagen's 'Site Layout Plan' drwg No WLL02A-EXG-04-00-D-K001-P05, detail plans & elevations drwg Nos WLL02A-EXG-05-ZZ-D-(K001-K013)-P01 and Pegasus' Group 'Landscape Strategy' drwg no P21-2533_EN_06E.

Site photography & equipment

- SONY ILCE-7M4
- Sigma 50mm f/1.4 DG HSM Art Lens for Sony
- GPS: Iphone 15- App: GPS OS
- Tripod: ARTCISE AS80C 63.8", Carbon Fiber Bowl Tripod.
- Panoramic Tripod Head: Andoer
- Precision Leveller: Andoer LP-64
- L-Bracket: Pig Iron LB-1
- Slide Plate: MENGES FNR-200 200mm 1/4"
- Quick Release Plate Clamp: Sequipr 50mm

Site verified photography

- 8.5. Using the Pegasus Group LVIA baseline viewpoints as a reference point, the camera body and lens were attached to a panoramic head with a leveller. A tripod was used and set to a height of 1.6m to represent the average height of the human eye. A fixed 50mm lens was used to ensure a consistent 50mm focal length across all photographs. 50mm is the industry standard for the visual representation of a development. 50mm has been chosen as the focal length which closely matches human eyesight and minimising optical distortion (please read the Landscape Institutes' guidance for more information)
- 8.6. Photographs were taken on 'Raw' and the camera metadata is stored with each photo. The photographs taken from the site visit were stitched together in PTGui to create the panoramas using the cylindrical layout method.

Modelling & visualisation production process

- 8.7. The photographs taken from the site visit were stitched together in Photoshop to create the panoramas using the cylindrical layout method.
- 8.8. An accurate geo-referenced 3D model was created by precisely combining the information mentioned in paragraph 8.4 with 1m LiDAR DSM (Digital Surface Model) terrain, a topographic survey (dwg No WLL02A- K- TopographicSurvey 3D_levels) and high resolution aerial photography into one universal 3D model.
- 8.9. FTR Visuals provided a Excel spreadsheet containing the viewpoint photograph coordinates (0134_Old Wood Energy Park.xlsx), these were input into the 3D model space using the OS British National Grid system (OS GB 1936). Virtual 'cameras' were then created and aligned to these coordinates, replicating the position, focal length/field of view and elevation of the original viewpoint photographs.
- 8.10. Common reference points were then added to the model. These reference points locate elements that can be seen in the view such as; existing building corners, roof apexes and lampposts. This method was used to aid in aligning the model to the real photographic image and to further increase the accuracy of the proposal's scale and position.
- 8.11. Exagen's Exagen's 'Site Layout Plan' drwg No WLL02A-EXG-04-00-D-K001-P05 provided the development parameters and the FFL's were based on existing site levels.
- 8.12. Typical material solar PV finishes were applied to the 3D model. These materials and textures were applied using Sketchup, Vray and 3Ds Max software. This rendering system also incorporates realistic lighting, by matching the same date, time of day and weather conditions as the viewpoint photographs. The resolution of the rendered image was matched to that of the viewpoint photographs, to allow for direct overlay, without further size adjustment.
- 8.13. At post-production stage, Photoshop software was used to allow for fine tuning of the integration of the proposed rendered image into the viewpoint photograph. This was where masking of the proposal, by existing obscuring features (including foreground vegetation and buildings) occurred.

*Landscape Institute (LI) Technical Guidance Note 06/19 'Visual Representation of Development Proposals'.

Reproduction

- 8.14. Due to the proximity of the views, the linear nature of the development and to capture enough context, A1 paper size was selected.
- 8.15. For these visual representations, the printed result allows for the viewer to make direct comparisons between the proposed viewpoint visualisations and the real-life existing view. This can be achieved by standing in-situ at the relevant viewpoint location and holding up the printed images at a comfortable arm's length. Please be sure the printed image is to scale
- 8.16. Each viewpoint is supplied with a viewpoint map, tripod location and the following metadata:
- Visualisation Type
 - Projection
 - Enlargement Factor
 - Date & time of photo
 - Camera/sensor
 - Camera lens
 - Camera height
 - Max aperture
 - HFoV
 - Distance to site
 - Direction
 - Frame Type
 - Viewpoint location
 - Viewpoint ground height
 - Sheet size
 - Weather
 - Visibility
 - Page viewing distance

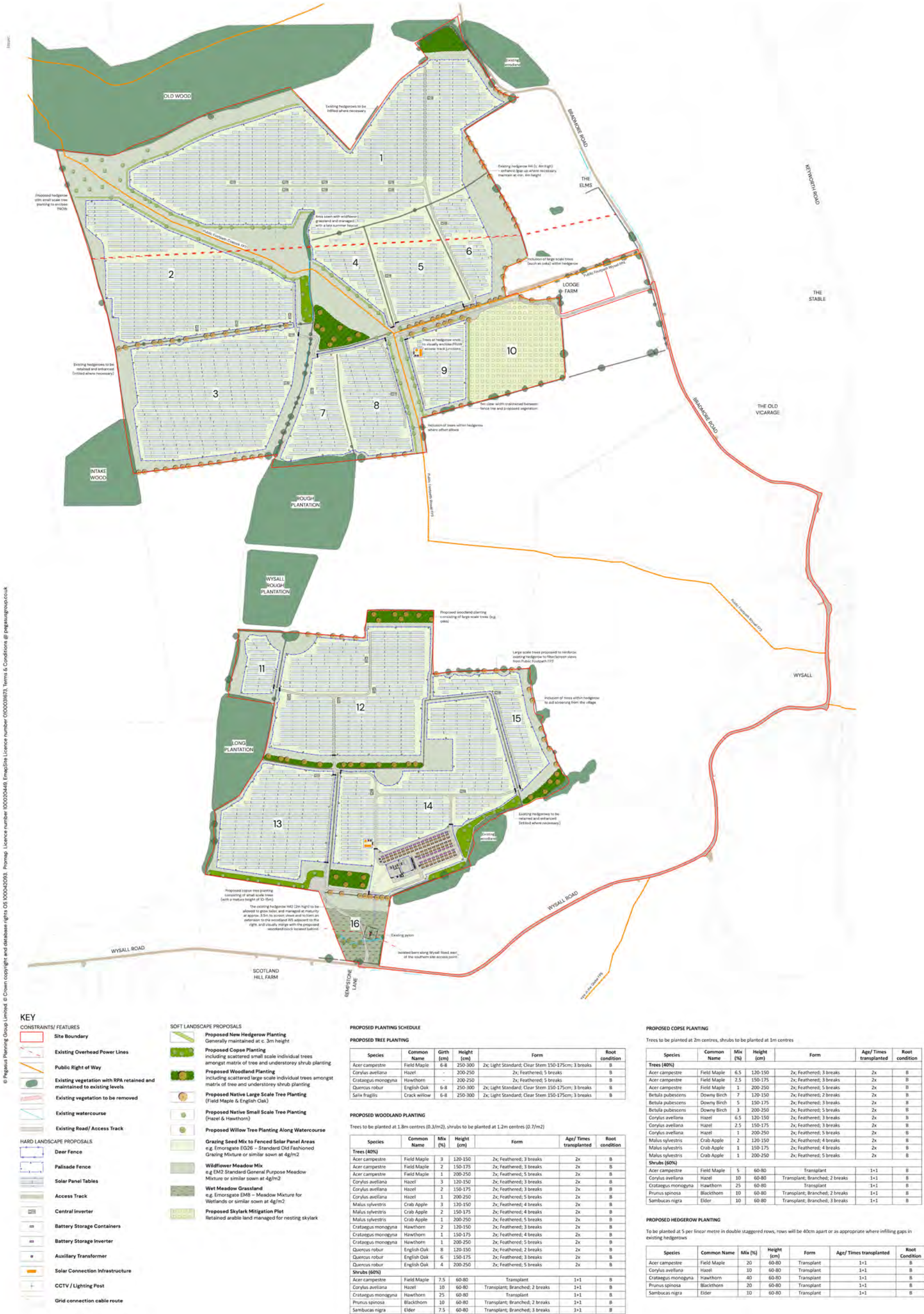
Limitations

- 8.17. TGN-06-19 Para 1.2.13 page 2 of 58 *“Two-dimensional visualisations, however detailed and sophisticated, can never fully substitute what people would see in reality. They should, therefore, be considered an approximation of the three-dimensional visual experiences that an observer might receive in the field.”*
- 8.18. Photograph locations were not surveyor measured as this was not considered proportionate.
- 8.19. The following visualisations are based on the layout submitted with the planning application and this may not be the same as the final as built design

9.0 Technical Methodology

Visualisation Types				Photography	Responses
1	2	3	4		
✓	✓	✓	✓	Visualisation Types Methodology	Yes- see page viewpoint location plan and view information page prior to visualisations.
		✓	✓	Method used to establish the camera location (e.g. handheld GPS/GNSS, GNSS/RTK, survey point, visual reference)	GPS: Iphone 15- App: GPS OS
		✓	✓	Likely level of accuracy of location (#m, #cm etc)	≤ 1m
		✓	✓	If lenses other than 50mm have been used, explain why a different lens is appropriate	N/A
			✓	Written description of procedures for image capture and processing	Yes- see section 8.0 Methodology
			✓	If panoramas used: make and type of Pano head and equipment used to level head	Panoramic Tripod Head: Andoer, Precision Leveller: Andoer LP-64
			✓	If working outside the UK, geographic co-ordinate system (GCS) used (e.g. WGS-84)	N/A
				3D Model / Visualisation	
		✓	✓	Source of topographic height data and its resolution	LiDAR 1m DSM (Digital Surface Model) and a topographical survey.
		✓	✓	How have the model and the camera locations been placed in the software?	Point coordinates added to geo-referenced dwg file containing topo survey and proposed layout. Points loaded into 3D program and camera added to points.
			✓	Elements in the view used as target points to check the horizontal alignment	Multiple existing features in photograph/view matched to topo plan, used a reference points/markers, camera automatically set to level horizontally
			✓	Elements in the view used as target points to check the vertical alignment	Multiple existing features in photograph/view are matched to topo plan, used a reference points/markers, camera automatically set to level vertical alignment
				Generally	
✓		✓	✓	Any limitations in the overall methodology for preparation of the visualisations?	The visual representations are based on an outline planning layout rather than a fully detailed scheme.

Visualisation Types				Photography	Responses
1	2	3	4		
✓	✓	✓	✓	Visualisation Type	Type 4
		✓	✓	Projection	Cylindrical (A1 panoramas)
		✓	✓	Enlargement factor for intended sheet size	96% and 150% (A1 panoramas)
		✓	✓	Date and Time of captured photography	Dates & times vary, see view information page prior to visualisations
			✓	Make and model of camera, and its sensor format	Camera models vary, see view information page prior to visualisations
			✓	Make, focal length of the camera lens(es) used.	Sigma 50mm f/1.4 DG HSM Art Lens for Sony and Canon EF 50mm f/1.8 fixed lens
			✓	Horizontal Field of View (HFOV) of photograph / visual	90° and 53.5°(A1 panoramas)
		✓	✓	Direction of View: bearing from North (0°) or Compass Direction	Bearings vary, see view information page prior to visualisations
		✓	✓	Camera location grid coordinates: eastings & northings to relevant accuracy; height of ground in mAOD	See view information page prior to visualisations
			✓	Distance to the nearest site boundary, or key development feature, as most appropriate.	See view information page prior to visualisations
			✓	Height of the camera lens above ground level and, if above 1.65m or below 1.5m, why?	1.6m
				Additional imagery	
✓		✓	✓	Baseline photograph	Existing view / baseline photograph included prior to visualisations
			✓	A composite view generated by overlaying multiple layers of image data: the photograph, 3D model of terrain (LiDAR DTM) and / or 3D model of LiDAR DSM, 3D model of proposed development, 3D model of landscape mitigation. This can explain how the photomontage has been generated.	Included to generate the visualisations
			✓	A photograph of the tripod location to confirm the camera / tripod location	Yes- see page viewpoint location plan and tripod location prior to visualisations



Town & Country Planning Act 1990 (as amended)
Planning and Compulsory Purchase Act 2004

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